Weighted Sampling for Scalable Analytics of Large Data Sets

Edith Cohen

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May 24, 2016



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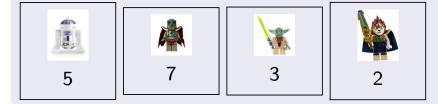
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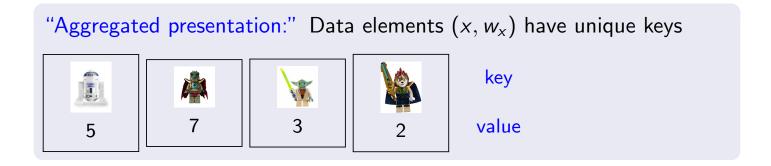
Key value pairs (x, w_x) (users/activity, IP flows/sizes)

"Aggregated presentation:" Data elements (x, w_x) have unique keys



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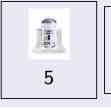
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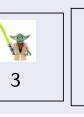
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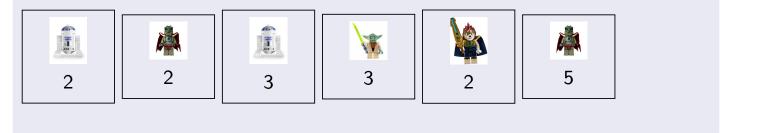




key value

"Unaggregated presentation:" (Streamed or distributed) Elements (x, w)of key and value w > 0; w_x is the sum of values of elements with key x.

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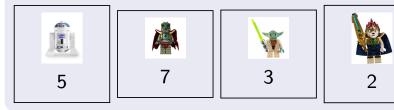
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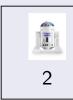
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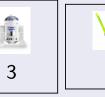


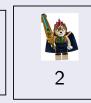
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key

value



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Queries are typically specified over the aggregated view

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$$Q(f,H)=\sum_{x\in H}f(w_x)$$

- Function $f(w) \ge 0$ for $w \ge 0$ so that f(0) = 0
- Selected segment $H \subset \mathcal{X}$ (domain, subpopulation) from all keys

Example f():

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Moments w^p with $p \in [0, 1]$ and cap statistics cap_T with $T \in (0, +\infty)$ parametrize the range between distinct and sum.

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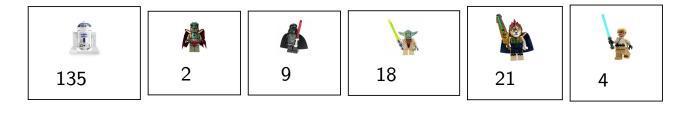
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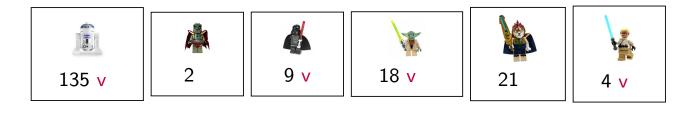
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Segment *H*: space travelers Q(count, H) = 4 $Q(cap_5, H) = 19$ $Q(thresh_{10}, H) = 2$

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Segment H: space travelers Q(count, H) = 4 $Q(cap_5, H) = 19$ $Q(thresh_{10}, H) = 2$

Segment *H*: Good guys

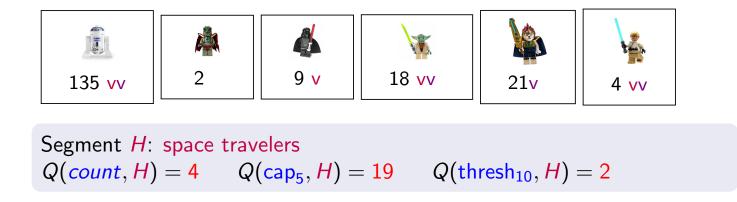
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Segment *H*: Good guys

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Segment *H*: space travelers Q(count, H) = 4 $Q(cap_5, H) = 19$ $Q(thresh_{10}, H) = 2$

Segment H: Good guys Q(count, H) = 4 $Q(ln(1 + w), H) \approx 12.56$

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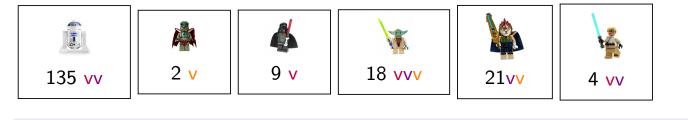
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Segment H: Good guys Q(count, H) = 4 $Q(ln(1 + w), H) \approx 12.56$

Q: Segment H: Non-human life Q(count, H) = 3 $Q(L_2^2, H) = 769$

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Challenges

Multi-objective sample (un)aggregated data: For a set of functions F, compute a summary/sample from which we can *estimate* Q(f, H) for various $f \in F$, $H \subseteq \mathcal{X}$.

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Weighted sample unaggregated data: For a given f, compute a summary/sample from which we can *estimate* Q(f, H) for various H

• Basic: Estimate Q(f, H) for a given $f, H \subseteq \mathcal{X}$

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Goals:

- Optimize tradeoffs of sample quality (statistical guarantees) and size.
- Scalable computation.

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Scalable Computation

One (or few) passes over the data

- Streaming (single sequential pass): Necessary for live dashboards and when data is discarded. Historically model captured sequential-access storage devices (tape, disks), Unix pipes.
 Streaming model: [Knu68], [MG82], [FM85],..., formalized in [AMS99]
- Distributed/Parallel aggregation: Process parts of the data separately and combine small summaries.

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Small state

- When streaming, the state is what we keep in memory
- In distributed aggregation, it is the summary size that is shared

We want state \ll number of (distinct) keys

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Challenge with unaggregated data: Computing the aggregated view $\{(x, w_x)\}$ requires state \propto number of active keys, which can be very large.

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• Aggregated data sets:

• Review the "gold standard" ^{Context} Sample size/ estimation quality tradeoffs.

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• Aggregated data sets:

- Review the "gold standard" ^{Sample} Sample size/ estimation quality tradeoffs.
- Multi-objective (MO) sampling
 - Coordinating samples for different $f \in F$
 - MO sampling scheme for all monotone (non-decreasing) f. [Coh15b]
 - MO sampling distances from query points. [CCK16]

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 - MO sampling distances from query points. [CCK16]
- Unaggregated data sets: How to sample effectively *without* aggregation for capping statistics (and more) [Coh15c]

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- Data provided as key value pairs (x, w_x) .
- Compute a sample S_f of size k from which we can estimate Q(f, H).

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To get good size/quality tradeoffs, need (roughly) $\Pr[x \in S_f] \propto f(w_x)$:

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- Poisson Probability Proportional to Size (PPS): Sample keys independently with $p_x = \min\{1, \frac{kf(w_x)}{\sum_x f(w_x)}\}$
- VarOpt [Cha82, CDL+11]: Dependent PPS for sample size exactly k

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Bottom-k/order/weighted reservoir sampling schemes [Ros97, CK07]

foreach key x do // Z[w]: distribution parameterized by w $\lfloor \operatorname{seed}(x) \sim Z[f(w_x)]$ $S \leftarrow k$ keys with smallest $\operatorname{seed}(x)$; $\tau \leftarrow (k+1)$ th smallest $\operatorname{seed}(x)$

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Aggregated data: Weighted sampling schemes

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- Sequential Poisson (priority) [Ohl98, DTL07]: seed(x) ~ $U[0, 1/f(w_x)]$
- PPS without replacement (ppswor) [Ros72]: seed(x) $\sim \text{Exp}[f(w_x)]$

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Inverse probability estimator of Q(g, H) from the sample S [HT52]

 $p_x = \Pr[x \in S]$: probability that key x is sampled For each key x, estimate $g(w_x)$ by 0 if $x \notin S$ and by $g(w_x)/p_x$ if $x \in S$.

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Poisson PPS samples: $p_x = \min\{1, \frac{kf(w_x)}{\sum_x f(w_x)}\}\$ We have w_x for sampled keys $x \in S$, and the total $\sum_x f(w_x)$ \implies can compute p_x and apply estimator.

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Bottom-k samples: p_x is not available so instead we use

$$p_{x|\tau} \equiv \Pr[\operatorname{seed}(x) < \tau] = \Pr[Z[f(w_x)] < \tau]$$

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The inclusion probability of x conditioned on randomization of all other keys: τ is the kth smallest seed(y) for $y \neq x$; $x \in S \iff \text{seed}(x) < \tau$

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- For ppswor $Z[y] \equiv \operatorname{Exp}[y]$: $p_{x|\tau} = 1 e^{-f(w_x)\tau}$
- For priority $Z[y] \equiv U[0, 1/y]$: $p_{x|\tau} = \min\{f(w_x)\tau, 1\}$

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Inverse probability estimator of Q(g, H) from the sample S [HT52]

 $p_x = \Pr[x \in S]$: probability that key x is sampled For each key x, estimate $g(w_x)$ by 0 if $x \notin S$ and by $g(w_x)/p_x$ if $x \in S$.

$$\hat{Q}(g,H) = \sum_{x\in H} \hat{g}(w_x) = \sum_{x\in H\cap S} \frac{g(w_x)}{p_x}$$

Applies when we can compute p_x for $x \in S$

• nonnegative (since g is) • unbiased (if $g(w_x) > 0 \implies f(w_x) > 0$)

Bottom-k samples: p_{x} is not available so instead we use

$$\mathbf{p}_{\mathbf{x}|\tau} \equiv \Pr[\texttt{seed}(\mathbf{x}) < \tau] = \Pr[Z[f(\mathbf{w}_{\mathbf{x}})] < \tau]$$

$$\hat{Q}(g,H) = \sum_{x \in H \cap S} \hat{g}(w_x \mid \tau)$$
, where $\hat{g}(w_x \mid \tau) = \frac{g(w_x)}{p_{x \mid \tau}}$.

How good is this estimate?

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Scalable Weighted Sampling

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Let $q \equiv q(f, H)$ be the fraction of the statistics f due to segment H:

$$q = rac{Q(f,H)}{Q(f,\mathcal{X})} = rac{\sum_{x\in H} f(w_x)}{\sum_x f(w_x)}$$

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bound on the Coefficient of Variation (CV) (relative standard deviation)

$$rac{\sqrt{ extsf{var}[\hat{Q}(f,H)]}}{Q(f,H)} \leq rac{1}{\sqrt{q(k-1)}}$$

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+concentration: sample size $k = c\epsilon^{-2}/q$ then prob. of rel. error > ϵ decreases exponentially in c.

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CV (relative standard deviation) bound

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CV (relative standard deviation) bound $\frac{\sqrt{\operatorname{var}[\hat{Q}(f,H)]}}{Q(f,H)} \leq \frac{1}{\sqrt{q(k-1)}}$ $\implies \text{ If we want CV} \leq \epsilon \text{ on segments } H \text{ that have } q(f,H) \geq q \text{ fraction} \text{ of the total } f \text{ statistics, we need a sample of size } k = \epsilon^{-2}/q$

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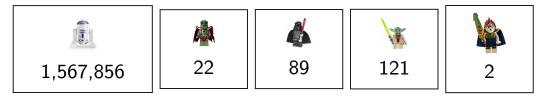
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CV (relative standard deviation) bound

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⇒ If we want $CV \le \epsilon$ on segments H that have $q(f, H) \ge q$ fraction of the total f statistics, we need a sample of size $k = \epsilon^{-2}/q$

!! This is the optimal size/quality tradeoff for sampling (on average over segments with proportion q)



For CV $\epsilon \leq 10\%$ and $q \geq 0.1\% \implies$ Sample size $k = 10^5$.

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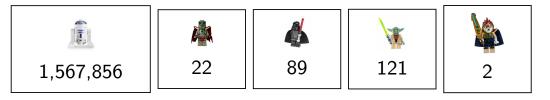
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For CV $\epsilon \leq 10\%$ and $q \geq 0.1\% \implies$ Sample size $k = 10^5$.

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... usually $k \ll$ total number of active keys.

Sample with respect to f, but estimate Q(g, H)

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Sample with respect to f, but estimate Q(g, H)

Disparity between *g*, *f*:

$$\rho(g, f) = \max_{w>0} \frac{g(w)}{f(w)} \max_{w>0} \frac{f(w)}{g(w)}$$

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- Disparity is always $\rho(g, f) \ge 1$.
- We have $\rho(g, f) = 1 \iff g = cf$ for some c.

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- We have $\rho(g, f) = 1 \iff g = cf$ for some c.

Lemma

CV of $\hat{Q}(g, H)$ is at most $(\frac{\rho}{q(k-1)})^{0.5}$.

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With a weighted sample of size $k = e^{-2}$ with respect to f, we estimate Q(f, H) with $CV \le e/\sqrt{q}$. But quality guarantee for Q(g, H) degrades with disparity $\rho(f, g)$.

What if we want quality guarantee of $CV \leq \epsilon/\sqrt{q}$ for several $f \in F$?

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Multi-objective samples [CKS09]

Approach

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Multi-objective samples [CKS09]

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 Make the dedicated samples for different *f* ∈ *F* as similar as possible. Sample Coordination [BEJ72, Coh97]: Similar samples *S_f* for similar *f*.

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• Work with the union sample, estimate using the inclusion probabilities in at least one dedicated sample.

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Multi-objective sample S_F [CKS09]

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Multi-objective sample S_F [CKS09]

S_F = ⋃_{f∈F} S_f is the union of *coordinated* bottom-k (or pps) samples for f ∈ F
 E.g. with priority sampling, draw u_x ~ U[0, 1] once, and for S_f use seed(x) = u_x/f(w_x).

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- For estimation, use p_x = Pr[x ∈ S_F] (inclusion in at least one dedicated S_f)
- Estimates have $CV \le \epsilon/\sqrt{q}$ for Q(f, H) for all $f \in F$.
- Size typically $\ll |F|\epsilon^{-2}$ (but is as small as possible).

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	x									X
	W_X	135	2	9	18	21	4	11	4	2
_										
	Count	1	1	1	1	1	1	1	1	1
	$cap_5(w_x)$	5	2	5	5	5	4	5	4	2
	$thresh_{10}$	1	0	0	1	1	0	1	0	0

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_	W _X	135	2	9	18	21	4	11	4	2
	Count	1	1	1	1	1	1	1	1	1
	$cap_5(w_x)$	5	2	5	5	5	4	5	4	2
	$thresh_{10}$	1	0	0	1	1	0	1	0	0
	U _X	0.52	0.24	0.76	0.90	0.14	0.32	0.44	0.07	0.82

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_	W_X	135	2	9	18	21	4	11	4	2
	Count	1	1	1	1	1	1	1	1	1
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	thresh ₁₀	1	0	0	1	1	0	1	0	0
_										
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	$\frac{u_{X}}{\text{thresh}_{10}(w_{X})}$	0.52	∞	∞	0.90	0.14	∞	0.44	∞	∞
	$\frac{u_X}{\operatorname{cap}_5(w_X)}$	0.104	0.120	0.152	0.18	0.064	0.080	0.088	0.0175	0.41

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W_X	135	2	9	18	21	4	11	4	2
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For k = 3, the MO sample for $F = {count, thresh_{10}, cap_5}$ is:

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MO Sample for all monotone functions

What can we say about MO sampling the set M of all monotone non-decreasing functions of w_x ?

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M includes all moment, capping, and threshold functions ...

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Theorem [Coh15b]

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What can we say about MO sampling the set M of all monotone non-decreasing functions of w_x ?

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Theorem [Coh15b]

• Size: $E[|S_M|] \le \epsilon^{-2} \ln n$, where *n* number of keys.

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Theorem [Coh15b]

- Size: $E[|S_M|] \le \epsilon^{-2} \ln n$, where *n* number of keys.
- Computation: S_M and inclusion probabilities used for estimation can be computed using $O(n \log e^{-1})$ operations.

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- Tight lower bound: When keys have distinct weights, any sample providing these statistical guarantees has size Ω(ε⁻² ln n). Enough to look at thresh functions (thresh_T(x) = 1 if x ≥ T and 0 otherwise)

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Sampling scheme builds on a surprising relation to computing All-Distances sketches [Coh97, Coh15a])

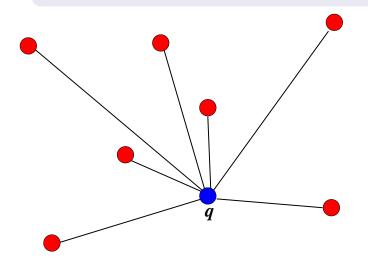
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MO Sample for single-source distances

Set U of points in a metric space M. Each point q defines $f_q(y) \equiv d_{qy}$, for all $y \in M$.



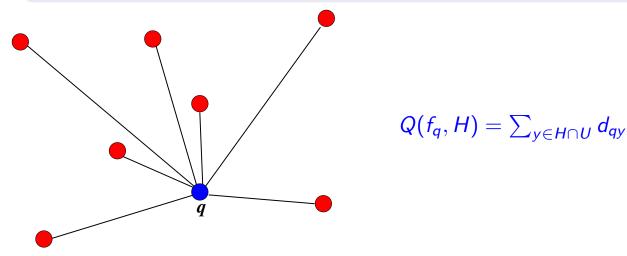
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MO Sample for single-source distances

Talk Overview

- Aggregated data sets: Review the "gold standard" ^{Sample} Sample size/ estimation quality tradeoffs.
- Multi-objective (MO) sampling
 - Coordinating samples for different $f \in F$
 - MO sampling scheme for all monotone (non-decreasing) f. [Coh15b]
 - MO sampling distances from query points. [CCK16]

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• Unaggregated data sets: How to sample effectively *without* aggregation for capping statistics (and more) [Coh15c]

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Summary: Aggregated data "gold standard" sampling

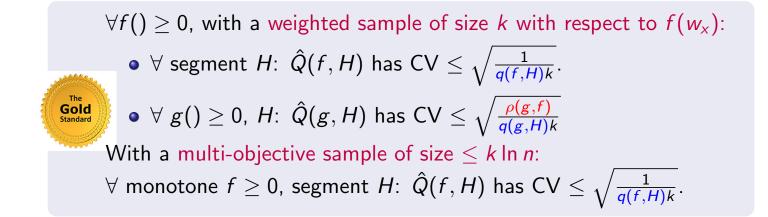
 $\forall f() \ge 0, \text{ with a weighted sample of size } k \text{ with respect to } f(w_{x}):$ • \forall segment $H: \hat{Q}(f, H)$ has $CV \le \sqrt{\frac{1}{q(f, H)k}}.$ • $\forall g() \ge 0, H: \hat{Q}(g, H)$ has $CV \le \sqrt{\frac{\rho(g, f)}{q(g, H)k}}$

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Summary: Aggregated data "gold standard" sampling



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Summary: Aggregated data "gold standard" sampling

 $\forall f() \geq 0, \text{ with a weighted sample of size } k \text{ with respect to } f(w_{x}):$ • \forall segment $H: \hat{Q}(f, H)$ has $CV \leq \sqrt{\frac{1}{q(f, H)k}}$.
• $\forall g() \geq 0, H: \hat{Q}(g, H)$ has $CV \leq \sqrt{\frac{\rho(g, f)}{q(g, H)k}}$ With a multi-objective sample of size $\leq k \ln n$: \forall monotone $f \geq 0$, segment $H: \hat{Q}(f, H)$ has $CV \leq \sqrt{\frac{1}{q(f, H)k}}$.

Desirables with unaggregated data (and $w_x \equiv \sum_{\text{elements } (x,w)} w$):

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- Computation: One or two passes, state $\propto k$ (no aggregated view!)
- Quality: Sample size/estimate quality tradeoff near gold standard.

Scalable Weighted Sampling

The first few impressions of the same ad per user are more effective than later ones (diminishing return). Advertisers therefore specify

- A segment of users (based on geography, demographics, other)
- Cap T on the number of impressions per user per time period.

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Q: targeted segment: galactic-scale travelers cap: 5

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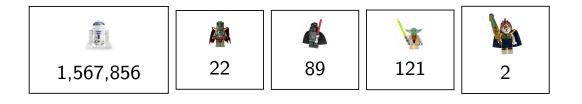
Q: targeted segment: galactic-scale travelers cap: 5 Answer (number of qualifying impressions): 15

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Q: targeted segment: galactic-scale travelers cap: 5 Answer (number of qualifying impressions): 15

Q: targeted segment: non-human intelligent life cap: 3

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Scalable Weighted Sampling

The first few impressions of the same ad per user are more effective than later ones (diminishing return). Advertisers therefore specify

- A segment of users (based on geography, demographics, other)
- Cap T on the number of impressions per user per time period.

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Q: targeted segment: galactic-scale travelers cap: 5 Answer (number of qualifying impressions): 15

Q: targeted segment: non-human intelligent life cap: 3 Answer (number of qualifying impressions): 8

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... Frequency Capping in Online advertising

Advertisers specify:

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Campaign planning is interactive. Staging tools use past data to predict the number $Q(cap_T, H)$ of qualifying impressions.

• Data is "unaggregated:" Impressions for same user come from diverse sources (devices, apps, times)

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 \implies Need quick estimates $\hat{Q}(cap_T, H)$ from a summary that is computed efficiently over the unaggregated data set.

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• Deterministic algorithms: Misra Gries: [MG82] Space saving [MAEA05] for heavy hitters

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- Deterministic algorithms: Misra Gries: [MG82] Space saving [MAEA05] for heavy hitters
- Random linear projections (linear sketches): Project vector of key values to a vector with logarithmic dimension. JL transform [JL84] and stable distributions [Ind01] for frequency moments p ∈ [0,2].

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- Sampling-based : Distinct Reservoir Sampling [Knu68] and MinHash sketches [FM85, Coh97] (distinct statistics), Sample and Hold [GM98, EV02, CDK⁺14] (sum statistics)

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No effective solutions for general capping statistics.

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Unifies classic schemes for distinct or sum statistics, generalizes bottom-k

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Unifies classic schemes for distinct or sum statistics, generalizes bottom-k

1. Scores of elements

Scheme is specified by a random mapping **ElementScore**(*h*) of elements h = (x, w) to a numeric score.

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Unifies classic schemes for distinct or sum statistics, generalizes bottom-k

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Properties of ElementScore: Distribution depends only on x and w. Can be dependent for same key, independent for different keys.

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2. Seeds of keys

The *seed* of a key x is the minimum score of all its elements.

 $seed(x) = \min_{h \text{ with key } x} ElementScore(h)$

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Unifies classic schemes for distinct or sum statistics, generalizes bottom-k

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3. Sample (S, τ)

 $S \leftarrow$ the k keys with smallest seed(x) (and their seed values)

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 $\tau \leftarrow$ the (k + 1)st smallest seed value.

Unaggregated data: VI, 2 3 5 3 2 2 The aggregated view: 7 3 5 2

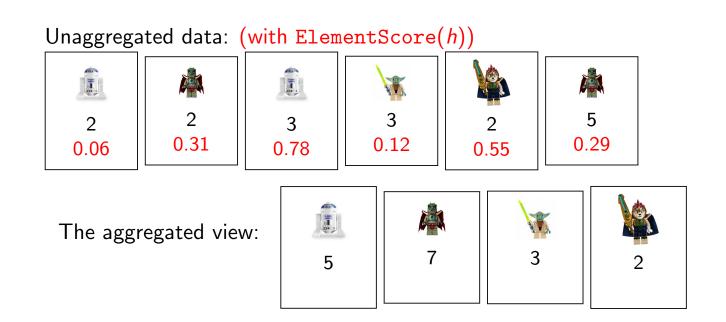
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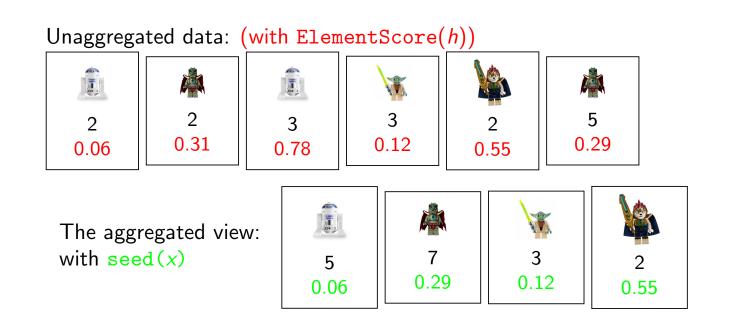
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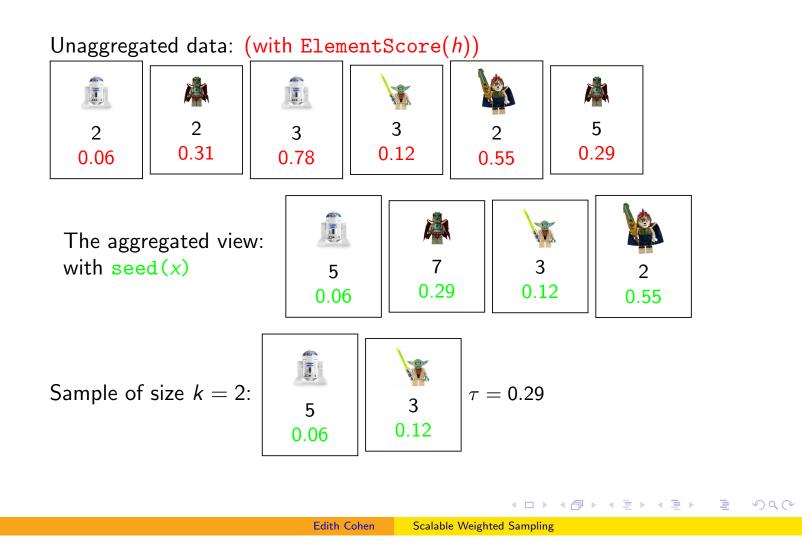
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Distinct sampling, casted in our framework

A distinct sample is a uniform sample of k active keys (keys with $w_x > 0$). Reservoir sampling [Knu68] +Hashing [FM85] [Vit85]

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Scoring for distinct sampling

ElementScore(h) = Hash(x), for random hash Hash(x) ~ U[0,1]

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From the point key x is included in S, we maintain a count c_x of the sum of weights of its elements. Since any key entered the sample on its first element, we have $c_x = w_x$.

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Each key x with $w_x > 0$ is sampled (conditioned on hashes of other keys) with probability $p_{x|\tau} \equiv \tau$.

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Each key x with $w_x > 0$ is sampled (conditioned on hashes of other keys) with probability $p_{x|\tau} \equiv \tau$.

We have w_x for each $x \in S$. Therefore, for any Q(f, H), we can compute the unbiased inverse probability estimate [HT52]:

$$\hat{Q}(f,H) = \sum_{x \in S \cap H} \frac{f(w_x)}{p_{x|\tau}} = \frac{1}{\tau} \sum_{x \in S \cap H} f(w_x) .$$

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Estimate quality: The sample and estimator are ppswor for distinct statistics.

 \implies For a segment H with proportion q, $\hat{Q}(distinct, H)$ has $CV \approx \sqrt{\frac{1}{qk}}$.

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Scalable Weighted Sampling

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⇒ For cap_T statistics, disparity is $\rho(distinct, cap_T) = T$. The bound on the CV of $\hat{Q}(cap_T, H)$ is $\sqrt{\frac{T}{qk}}$. Intuitively, our sample can easily miss "heavy" keys with high cap_T(w_x) values which contribute more to the statistics.

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Sampling for sum statistics

Sample and Hold (counting samples) [GM98, EV02]:

If $x \in S$, increment c_x . Otherwise, cache if rand() $< \tau$.

Can be used with a fixed-size sample k; Equivalent to ppswor [CDK+14]; Continuous version (element weights) [CCD11].

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Sample and Hold casted in our framework:

Element scoring function

 $\texttt{ElementScore}(h=(x,w)) \sim \mathsf{Exp}[w]$

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The minimum of independent exponential random variables is an exponential random variable with a parameter that is the sum of their parameters. We get

$$seed(x) \sim \min_{\text{elements}(x,w)} Exp[w] \equiv Exp[w_x] \implies ppswor wrt w_x!$$

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Caveat! We do have a ppswor sample S and the threshold τ , but **exact** weights w_x for $x \in S$ are needed for the inverse probability estimator. When streaming (single pass), we can start "counting" w_x only after x enters the cache, so we may miss some elements and only have $c_x < w_x$.

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Solutions:

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Solutions:

• 2-passes: Use the first pass to identify the set *S* of sampled keys. Use a second pass to exactly count *w_x* for sampled keys. Apply ppswor inverse probability estimator.

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Solutions:

- 2-passes: Use the first pass to identify the set S of sampled keys. Use a second pass to exactly count w_x for sampled keys. Apply ppswor inverse probability estimator.
- Work with c_x: For estimating sum statistics, we can add expected weight of missed prefix [GM98, EV02, CDK+14] (discrete) [CCD11] (continuous) to each sampled key in segment to obtain an unbiased estimate.

Possible to estimate unbiasedly general f... [CDK+14] (discrete) [Coh15c] (continuous)... more later.

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ℓ-capped sampling [Coh15c]



Hurdle 1

To obtain a sample with gold standard quality for cap_{ℓ} , we need element scoring that would result in inclusion probability roughly proportional to $cap_{\ell}(w_x)$

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ℓ-capped sampling [Coh15c]



Hurdle 1

To obtain a sample with gold standard quality for cap_{ℓ} , we need element scoring that would result in inclusion probability roughly proportional to $cap_{\ell}(w_x)$



Hurdle 2

Streaming: Even if we have the "right" sampling probabilities, when using a single pass we need estimators that work with observed counts c_x instead of with w_x

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ℓ-capped sampling: Hurdle 1 🖆

Obtaining inclusion probabilities roughly proportional to $\operatorname{cap}_{\ell}(w_x)$ Each key has a base hash $\operatorname{KeyBase}(x) \sim U[0, 1/\ell]$, obtained using $\operatorname{KeyBase}(x) \leftarrow \operatorname{Hash}(x)/\ell$. An element h = (x, w) is assigned a score by first drawing $v \sim \operatorname{Exp}[w]$ and then returning v if $v > 1/\ell$ and $\operatorname{KeyBase}(x)$ otherwise:

element scoring for ℓ -capped samples

 $\texttt{ElementScore}(h) = (v \sim \mathsf{Exp}[w]) \le 1/\ell$? KeyBase(x) : v

The Exp[w] draws are independent for different elements and independent of KeyBase(x).

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ℓ-capped sampling: Hurdle 1 🖆

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- For keys with $w_x \ll \ell$, this is like ppswor wrt w_x
- For keys with $w_x \gg \ell$, this is like distinct sampling

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With 2-passes, we have w_x , can compute inclusion probabilities from τ and the distribution, and apply the inverse probability estimator.

Theorem

The CV of estimating $Q(cap_T, H)$ from an ℓ -capped sample of size k with exact weights w_x is at most

$$\left(\frac{e}{e-1}\frac{\max\{T/\ell,\ell/T\}}{q(k-1)}\right)^{0.5}$$

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- $\rho = \max\{T/\ell, \ell/T\}$ is the disparity between cap_{ℓ} and cap_{T} .
- Overhead factor of $(\frac{e}{e-1})^{0.5} \approx 1.26$ over aggregated "gold standard."

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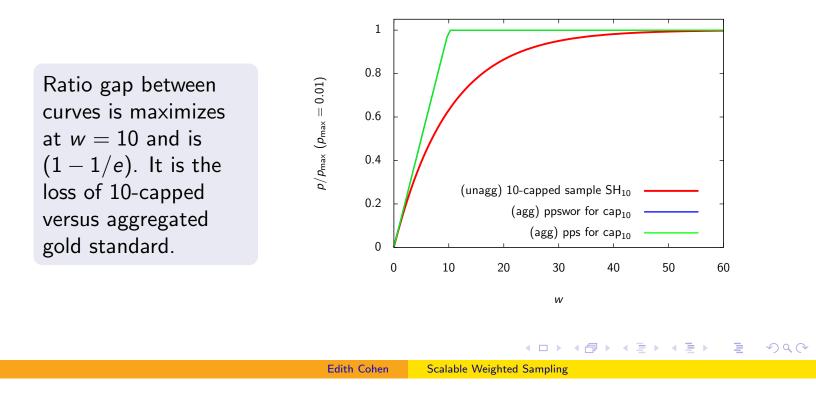
• This is a worst case factor (many items with $w_x = O(\ell)$)

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Estimation quality: 2-pass vs. gold standard

10-capped sample, pps and ppswor with weights $cap_{10}(w)$.

- x axis: the key weight w
- y axis: ratio of inclusion probability to max inclusion probability (set to 0.01).



The streaming algorithm maintains an "observed count" c_x for $x \in S$:

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Scalable Weighted Sampling

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• When we process an element h = (x, w) and $x \in S$, we increase $c_x \leftarrow c_x + w$.

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 $\implies c_x$ is an r.v. with distribution $\sim D[\tau, \ell, w_x]$.

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$$\hat{Q}(f,H) = \sum_{x\in H\cap S} \beta^{(f,\tau,\ell)}(c_x) .$$

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Where

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Where

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* Applies when f is continuous and differentiable almost everywhere (this includes all monotone functions)

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Streaming estimator quality

Theorem

The CV of the streaming estimator $\hat{Q}(cap_T, H)$ applied to an ℓ -capped sample is upper bounded by

$$\left(rac{rac{e}{e-1}(1+\max\{\ell/T,\,T/\ell\})}{q(k-1)}
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Worst-case overhead over aggregated "gold standard."

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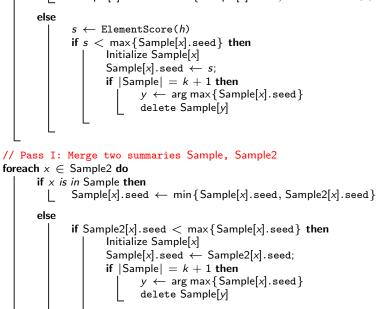
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(pseudo) Code: Fixed-k 2-pass distributed ℓ -capped sampling

// Pass I: Identify k keys in Sample

// Pass I: Thread adds elements to local summary Sample $\leftarrow \emptyset$ // Initialize max heap/dict of key seed pairs foreach element h = (x, w) do if x is in Sample then Sample[x].seed $\leftarrow \min{Sample[x].seed, ElementScore(h)}$



// Pass II: Compute w_x for keys in Sample

// Pass II: Process elements in thread foreach $x \in$ Sample do // Initialize thread $[Sample[x]. w \leftarrow 0$

// Pass II: Merge two summaries Sample, Sample2 foreach $x \in$ Sample do Sample[x]. $w \leftarrow$ Sample[x].w + Sample2[x].w

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(pseudo) Code: Fixed-k stream ℓ -capped sampling

foreach stream element (x, w) do // Process element if x is in Counters then Counters[x] \leftarrow Counters[x] + w; else $\Delta \leftarrow -\frac{\ln(1-\texttt{rand}())}{\max\{\ell^{-1},\tau\}} / / \sim \mathsf{Exp}[\max\{\ell^{-1},\tau\}]$ if $\Delta < w$ and $(au \ell > 1 \; {\it or} \; au \ell \leq 1$ and <code>KeyBase(x)</code> < au) then // <code>insert x</code> Counters $[x] \leftarrow w - \Delta$ if |Counters| = k + 1 then // Evict a key if $\tau \ell > 1$ then foreach $x \in$ Counters do $u_X \leftarrow \text{rand}(); r_X \leftarrow \text{rand}(); z_X \leftarrow \min\{\tau u_X, \frac{-\ln(1-r_X)}{\text{Counters}[x]}\} / / x's \text{ evict threshold}$ $\underset{L}{\text{if } z_X} \stackrel{\leq \ell^{-1}}{\underset{Z_X}{\leftarrow}} \underset{\leftarrow}{\text{KeyBase}(x)}$ $y \leftarrow \arg \max_{x \in \text{Counters } z_x}$; delete y from Counters // key to evict $\tau^* \leftarrow z_y / /$ new threshold for each $x \in \text{Counters do // Adjust counters according to } \tau^*$ if $u_X > \max\{\tau^*, \ell^{-1}\}/\tau$ then $\begin{bmatrix} \text{Counters}[x] \leftarrow \frac{-\ln(1-r_X)}{\max\{\ell^{-1}, \tau^*\}} \end{bmatrix}$ $\tau \leftarrow \tau^*$; delete u, r, z, b // deallocate memory else // $\tau \ell \leq 1$ $y \leftarrow \arg \max_{x \in \text{Counters}} \text{KeyBase}(x); \text{ Delete } y \text{ from Counters // evict } y$ $\tau \leftarrow \text{KeyBase}(y) / / \text{new threshold}$

 $return(\tau; (x, Counters[x]) \text{ for } x \text{ in Counters})$

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Simulations

CV upper bounds of $\sqrt{\rho \frac{e}{e-1}/(qk)}$ (2-pass) and $\sqrt{\frac{e}{e-1}(1+\rho)/(qk)}$ (1-pass) are worst-case.

What is the behavior on realistic instances ?

- Quantify gain from second pass
- Understand actual dependence on disparity
- How much do we gain from skew (as in aggregated data) ?

Experiments on Zipf distributions:

- Zipf parameters $\alpha \in [1, 2]$
- Segment=full population
- Swept query cap T and sampling-scheme cap ℓ .

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Simulation Results for *l*-capped samples

Zipf with parameter $\alpha = 2$, sample size k = 50, $m = 10^5$ elements. NRMSE (500 reps) of estimating $Q(cap_T, \mathcal{X})$ from ℓ -capped sample.

1-pass:	k = 5	50, $lpha$ =	= 2, <i>n</i>	n = 10)0000,	rep =	= 500,	NRMS	Ε
<i>ℓ</i> , <i>T</i>	1	5	20	50	100	500	1000	10000	
0.1	0.126	0.159	0.216	0.274	0.326	0.502	0.597	1.061	
1	0.129	0.141	0.192	0.244	0.293	0.449	0.526	0.908	
5	0.193	0.138	0.146	0.173	0.202	0.300	0.353	0.626	
20	0.277	0.169	0.124	0.118	0.125	0.183	0.216	0.377	
50	0.339	0.206	0.140	0.108	0.094	0.096	0.108	0.182	
100	0.390	0.236	0.146	0.107	0.085	0.046	0.034	0.022	
500	0.397	0.250	0.162	0.114	0.092	0.047	0.034	0.012	
1000	0.396	0.232	0.150	0.108	0.083	0.042	0.031	0.011	
10000	0.404	0.244	0.155	0.114	0.085	0.043	0.032	0.012	

2-pass:	k = 5	50, $lpha$:	= 2, n	n = 10	,0000	rep =	= 500,	NRMSE
<i>ℓ</i> , <i>T</i>	1	5	20	50	100	500	1000	10000
0.1	0.125	0.159	0.216	0.274	0.326	0.502	0.597	1.061
1	0.127	0.139	0.190	0.244	0.293	0.449	0.526	0.908
5	0.178	0.137	0.144	0.172	0.202	0.300	0.353	0.626
20	0.235	0.163	0.123	0.116	0.125	0.183	0.216	0.378
50	0.282	0.184	0.133	0.106	0.093	0.094	0.106	0.181
100	0.327	0.204	0.140	0.105	0.083	0.041	0.030	0.020
500	0.321	0.218	0.152	0.114	0.089	0.042	0.030	0.010
1000	0.322	0.208	0.143	0.105	0.080	0.039	0.028	0.009
10000	0.326	0.213	0.147	0.109	0.084	0.040	0.028	0.010

Worst-case: $0.14 \times 1.26 \times \sqrt{\rho} \approx 0.17 \sqrt{\rho}$ (2-pass) $0.17 \times \sqrt{1+\rho}$ (1-pass)

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Observations from Simulations

- Actual NRMSE is lower than worst-case:
 - We do not see the $\sqrt{e/(e-1)}$ factor (comes in when many keys have $w_x \approx \ell$).
 - Gain from skew: Observed for large T
 - Note that when $T \ll \ell$, skew can hurt us on "worst-case" segments of many light keys

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 - Gain from skew: Observed for large T
 - Note that when $T \ll \ell$, skew can hurt us on "worst-case" segments of many light keys
- Much better to use $\ell \approx T$
- 2-pass estimation quality is within 10% of 1-pass (⇒ use 2-pass to distribute computation but not to improve estimation)

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Summary:

• Aggregated data: Optimal multi-objective sampling scheme for all monotone *f*

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Summary:

- Aggregated data: Optimal multi-objective sampling scheme for all monotone *f*
- Unaggregated data: Sampling framework which unifies and extends classic solutions for distinct and sum statistics.
- Solution for cap_T statistics, nearly matches aggregated gold standard.

Scalable Weighted Sampling

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• Which other monotone frequency functions can our framework handle, in near "aggregated gold standard" sense?

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 - Can also obtain a multi-objective sample for these functions (logarithmic factor on sample size)

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- Some f with super-linear growth (p ∈ (1, 2] moments) is handled by linear sketches [Ind01, MW10] but not by samples.
- Can we support signed updates where f(max{0, w})? Perhaps use [GLH06, CCD12, Coh15c].

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- Can we do other aggregates of the elements of a given key ?

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- (functions of) Sum: here
- (functions of) max: small extension to aggregated sampling (through sample coordination)
- what other aggregations are interesting and can be handled ?

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Natural Questions (with partial answers):

- Which other monotone frequency functions can our framework handle, in near "aggregated gold standard" sense?
- Can we do other aggregates of the elements of a given key ?
- If we only want $Q(cap_T, \mathcal{X})$, can we do better ?
 - Is there a "Hyperloglog like" [FFGM07] algorithm with sketch size $O(\epsilon^{-2} + \log \log n)$ (instead of $O(\epsilon^{-2} \log n)$) ?

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• Can we use HIP estimators? [Coh15a, Tin14]

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Thank you!

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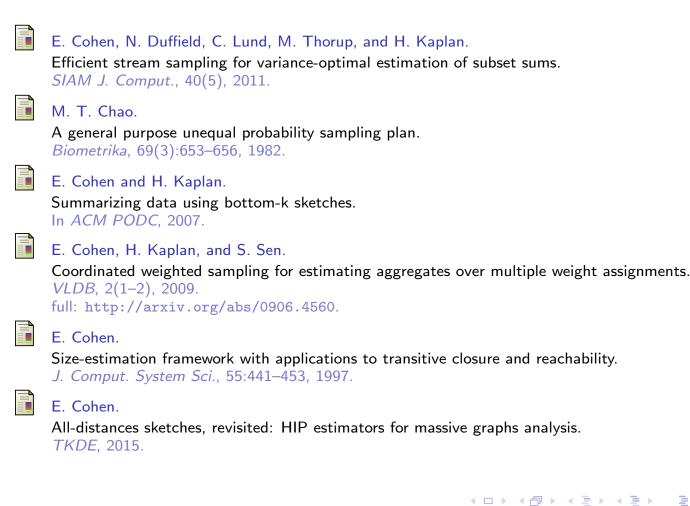
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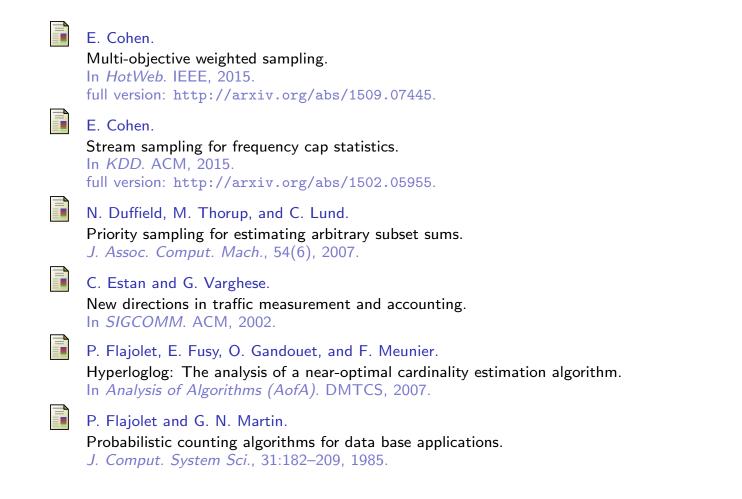
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