What you can do with Coordinated Sampling

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The Item-Function Estimation Problem

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IFE instance (V, \tau, f):
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- ➢ Data domain $V ⊂ R^r$
- \succ Scalar au
- \succ A function $f: V \ge 0$

Sampling scheme: Applied to data $v \in V$ to obtain a sample S

- > Draw random seed $u \sim U[0,1]$
- $\succ \text{ Include } v_i \in S \leftrightarrow v_i \geq \tau \cdot u$

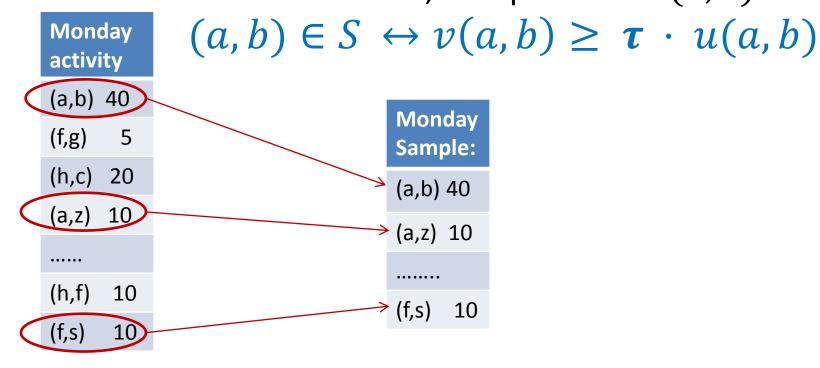
Goal: estimate f(v) from S and u: specify an estimator $\hat{f}(S, u)$

> A Less general formulation is used for this talk: τ can be different in each coordinate and we can use a general non-decreasing $\tau(u)$

Scenario: Social/Communication data

Activity value v(b,c) is associated with each node pair (b,c) (e.g. number of messages, communication)

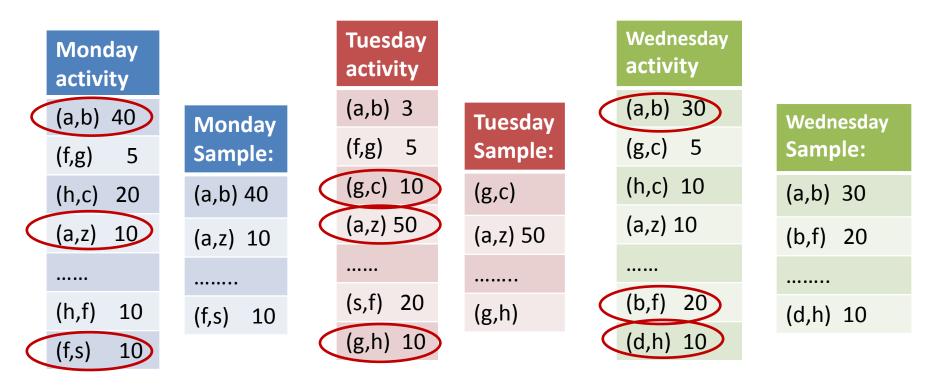
Pairs are *PPS sampled* (Probability Proportional to Size) For some $\tau > 0$, independent u(a, b):



Samples of multiple days

Coordinated samples: Each pair is sampled with same seed u(a, b) in different days

Example Queries: L_p difference (over selected pairs)



Back to the IFE problem

Many interesting queries:

 L_p difference, distinct counts, quantile sums,

can be expressed as sums (or simple functions of such sums) over selected items h of a function f applied to the values tuple of h

$$\boldsymbol{v}^{(h)} = (v^{(h)}_{1}, v^{(h)}_{2}, v^{(h)}_{3}, ...)$$

 $\sum_{h} f(\boldsymbol{v}^{(h)}) \quad \longleftarrow \text{For } L_p \text{ difference: } f(\boldsymbol{v}) = |v_1 - v_2|^p$

We can apply a linear (sum) estimator

 $\sum_{h} \hat{f}(\boldsymbol{v}^{(h)}) \quad \Leftarrow \text{ Each summand is an IFE estimator}$

Why Coordinate Samples?

- Minimize overhead in repeated surveys (also storage) Brewer, Early, Joice 1972; Ohlsson '98 (Statistics) ...
 - Can get better estimators

Broder '97; Byers et al Tran. Networking '04; Beyer et al SIGMOD '07; Gibbons VLDB '01; Gibbons Tirthapurta SPAA '01; Gionis et al VLDB '99; Hadjieleftheriou et al VLDB 2009; Cohen et al '93-'13

Sometimes cheaper to compute Samples of neighborhoods of all nodes in a graph in linear time Cohen '93 ...

Coordination had been used for 40+ years. Many applications and independent lines of research. It is time to understand it better.

Desirable Estimator Properties

? When can we obtain an estimator $\hat{f}(S, u)$ that is:

- Unbiased: because bias adds up
- Nonnegative: because f is
- Bounded variance (for all ν)
- Bounded by a function of f(v) (implies bounded variance)

Our Results (1)

Complete characterization in terms of (V, τ, f) for when the IFE instance has an estimator which is. >Unbiased and Nonnegative

Unbiased, Nonnegative, and has bounded variances
Unbiased, Nonnegative, and bounded

Variance Competitiveness

What about getting a "good" estimator $\hat{f}(S, u)$?

- Unbiased, Nonnegative, Bounded variance estimators are not unique
- No *UMVUE* (Uniform Minimum Variance Unbiased estimator) in general.

An estimator $\hat{f}(S, u)$ is *c***-competitive** if for any data v, the expectation of the square is within a factor **c** of the minimum possible for v (by an unbiased and nonnegative estimator).

For all unbiased nonnegative \hat{g} , $E[\hat{f}^2(S,u) | v] \leq c E[\hat{g}^2(S,u) | v]$

Our Results (2)

Thm: For any IFE instance (V, τ, f) for which an unbiased, nonnegative, and bounded-variances estimator exists, we can construct an estimator that is **O(1)-competitive** (84-competitive).

- In particular, we establish the **existence** of variance competitive estimators
- The construction is fairly efficient given reasonable representation of τ , f

What is the minimum variance for data v ?

An important tool we use (to bound competitiveness and establish existence of bounded-variance estimator):

For data v, we give an explicit construction of a "partial" estimator, $\hat{f}^{(v)}$, defined only on outcomes consistent with v. The estimates $\hat{f}^{(v)}$ minimize the variance for vunder the constraint that the partial specification

 $\hat{f}^{(v)}$ can be completed to an estimator that is unbiased and nonnegative everywhere.

> We give the intuition for this construction.

> Turns out that $\hat{f}^{(v)}$ is unique.

The lower bound function

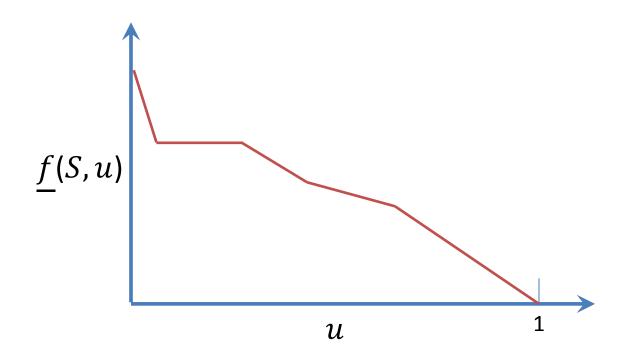
For an outcome and seed (S,u) we can look at the set of all consistent data vectors: $V^*(S, u)$

e.g. For S = (2,*,*) and seed u, the set of consistent vectors includes all vectors where the second and third entries are at most $u \tau$.

The lower bound f(S,u) is the infimum of f on $V^*(S,u)$

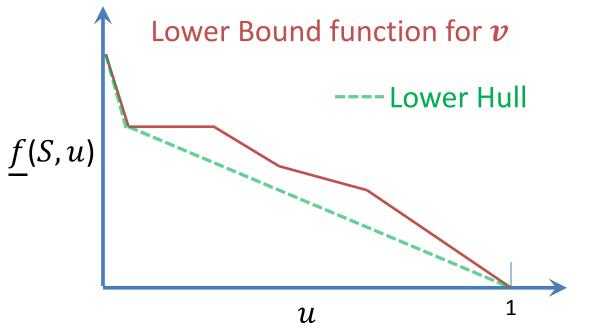
Lower bound function for data v

Fix the data v. Consider the lower bound $\underline{f}(S, u)$ as a function of the seed u. The lower u is, the more we know on v and hence on f(v). Therefore, f(S, u) is non-decreasing



Optimal estimates $\hat{f}^{(v)}$ for data v

The optimal estimates $\hat{f}^{(v)}$ are the negated derivative of the lower hull of the Lower bound function.



Intuition: The lower bound tell us on outcome S, how "high" we can go with the estimate, in order to optimize variance for v while still being nonnegative on all other consistent data vectors.

Follow-up work + Open problems

Studied range of Pareto optimal (admissible) estimators:

Natural estimators: L* (lower end of range: unique monotone estimator, dominates HT), U* (upper end of range), order optimal estimators (optimized for certain data patterns)

Obtained tighter competitiveness bounds: L* is 4 competitive, can do 3.375 competitive, lower bound is 1.44 competitive. Close this gap!

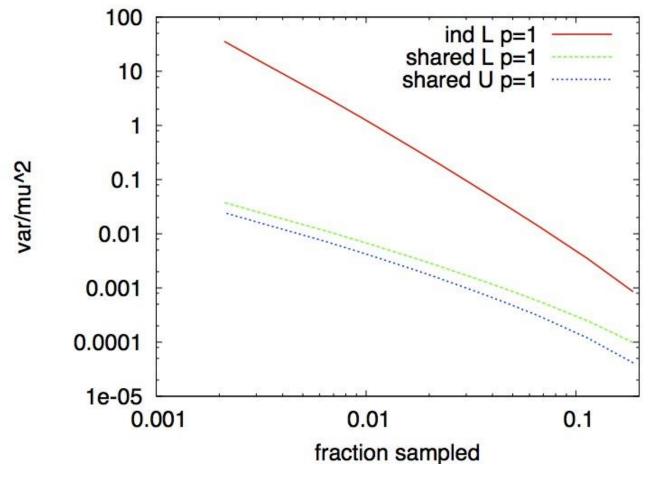
- > Instance-optimal competitiveness Give efficient construction for any IFE instance (V, τ, f) .
- Independent Sampling [CK PODS '11] A similar characterization ?
- Back to practice: Difference norms on sampled data [CK '13], sketch-based similarity in social networks [CDFGGW COSN '13].



Estimating L₁ difference

Independent / Coordinated, pps, known seeds

destination IP addresses: #IP flows in two time periods



Estimating L_2^2 difference

Independent / Coordinated, pps, Known seeds Surname occurrences in 2007, 2008 books (Google ngrams)

